	Type	L #	Hits	Search Text	DBs	Time Stamp
1	BRS	L1	258	((inertia$1 near3 sensor) or (dead near3 reckon$3) or acceler$8 or gyro$8) same phase same differen$3 same (correct$6 or compensat$6) same (drift or error)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 16:09
2	BRS	L2	3	1 and triangulat$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 12:18
3	BRS	L4	30	((inertia$1 near3 sensor) or (dead near3 reckon$3) or acceler$8 or gyro$8) same phase same differen$3 same (correct$6 or compensat$6) same (drift or error) same interfer$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 15:51
4	BRS	L5	228	1 not 4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 15:51
5	BRS	L6	19	((inertia$1 near3 sensor) or (dead near3 reckon$3) or acceler$8 or gyro$8) same phase same differen$3 same (correct$6 or compensat$6) same (drift or error) same (antennas or receiver)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 15:52
6	BRS	L7	17	6 not 4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 15:52
7	BRS	L8	1	((inertia$1 near3 sensor) or (dead near3 reckon$3) or acceler$8 or gyro$8) same phase same differen$3 same (correct$6 or compensat$6) same (drift or error) same triangulat$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 16:10
8	BRS	L9	3	(((inertia$1 near3 sensor) or (dead near3 reckon$3) or acceler$8 or gyro$8) same phase same differen$3 same (correct$6 or compensat$6) same (drift or error)) and triangulat$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 16:12
9	BRS	L10	7	(((inertia$1 near3 sensor) or (dead near3 reckon$3) or acceler$8 or gyro$8) same phase same (correct$6 or compensat$6) same (drift or error)) and triangulat$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2003/09/04 16:12